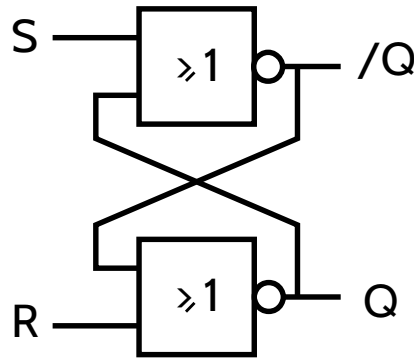
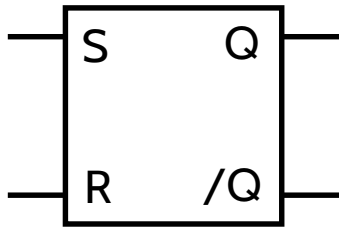


# Électronique Numérique

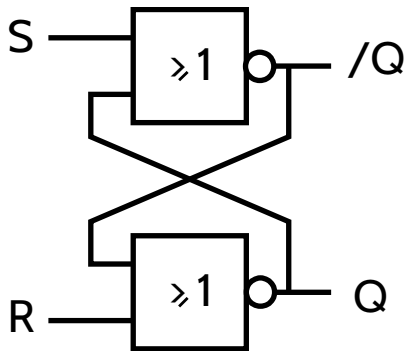
## Les bascules

# Le bistable RS



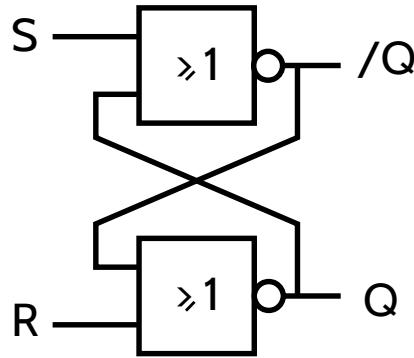
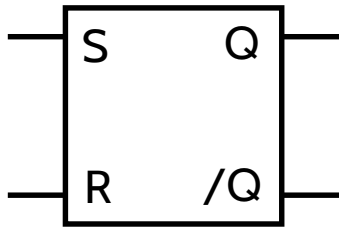
S : Set, entrée de mise à 1  
R : Reset, entrée de mise à 0

- Analyse



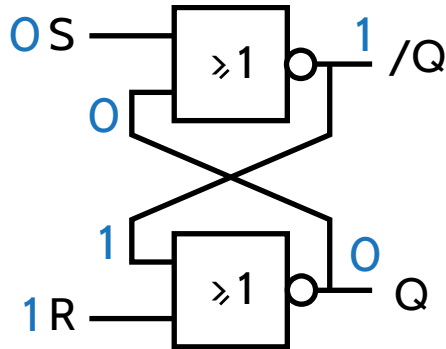
| S | R | Q |
|---|---|---|
| 0 | 0 |   |
| 0 | 1 |   |
| 1 | 0 |   |
| 1 | 1 |   |

# Le bistable RS



S : Set, entrée de mise à 1  
R : Reset, entrée de mise à 0

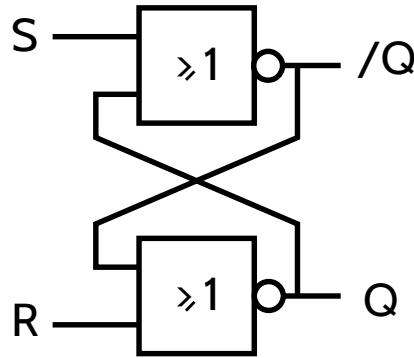
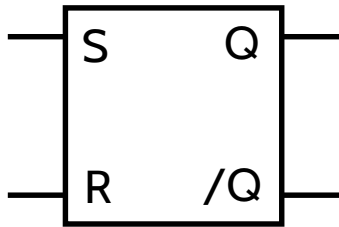
- Analyse



$$\overline{1+x} = 0$$

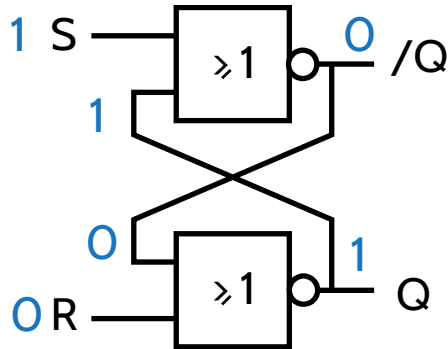
| S | R | Q |
|---|---|---|
| 0 | 0 |   |
| 0 | 1 | 0 |
| 1 | 0 |   |
| 1 | 1 |   |

# Le bistable RS



S : Set, entrée de mise à 1  
R : Reset, entrée de mise à 0

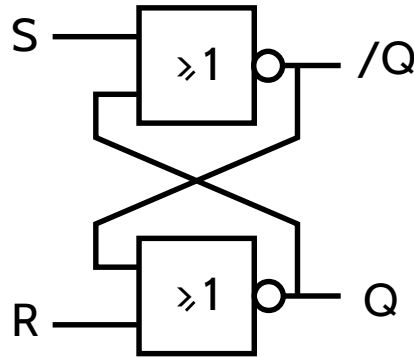
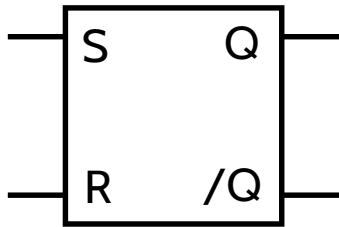
- Analyse



$$\overline{1+x} = 0$$

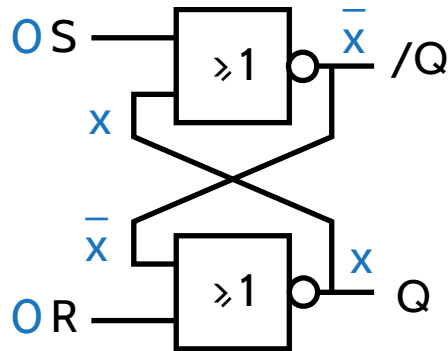
| S | R | Q |
|---|---|---|
| 0 | 0 |   |
| 0 | 1 | 0 |
| 1 | 0 | 1 |
| 1 | 1 |   |

# Le bistable RS



S : Set, entrée de mise à 1  
R : Reset, entrée de mise à 0

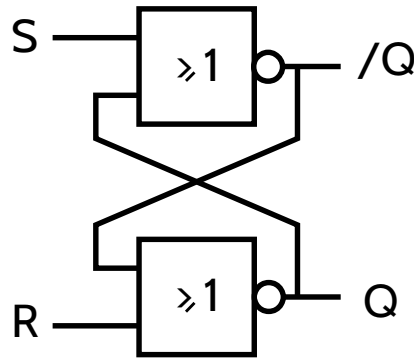
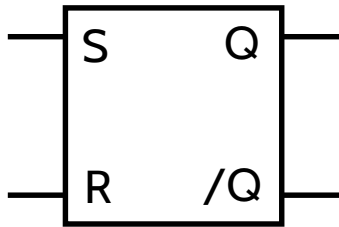
- Analyse



$$\overline{0 + x} = \bar{x}$$

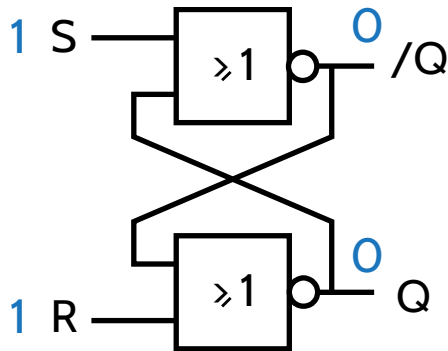
| S | R | Q         |
|---|---|-----------|
| 0 | 0 | inchangée |
| 0 | 1 | 0         |
| 1 | 0 | 1         |
| 1 | 1 |           |

# Le bistable RS



S : Set, entrée de mise à 1  
R : Reset, entrée de mise à 0

- Analyse



$$\overline{1+x} = 0$$

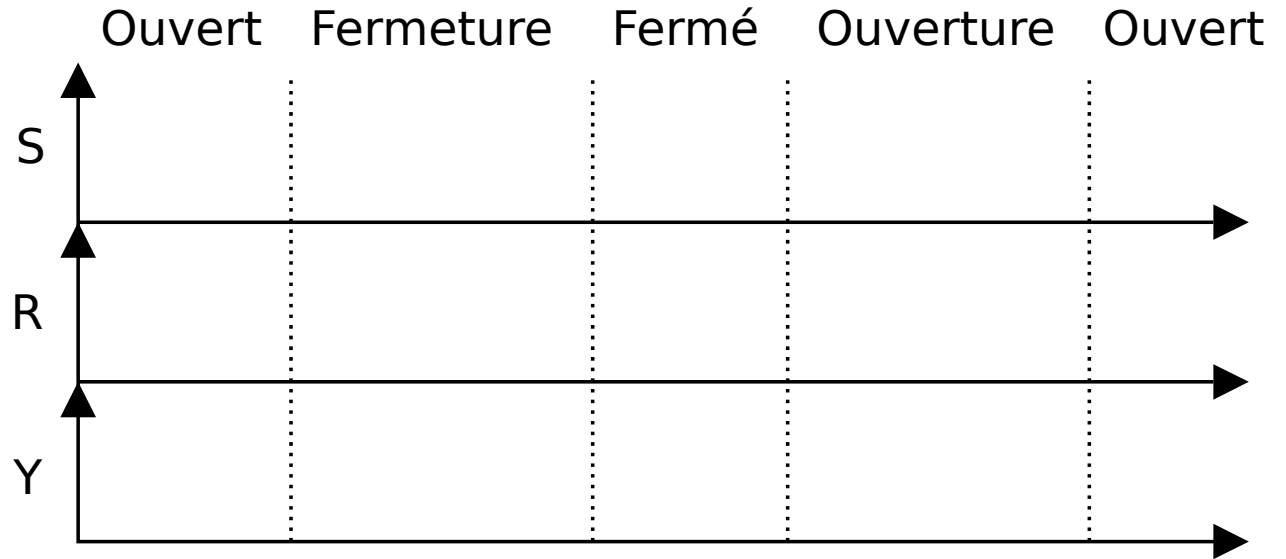
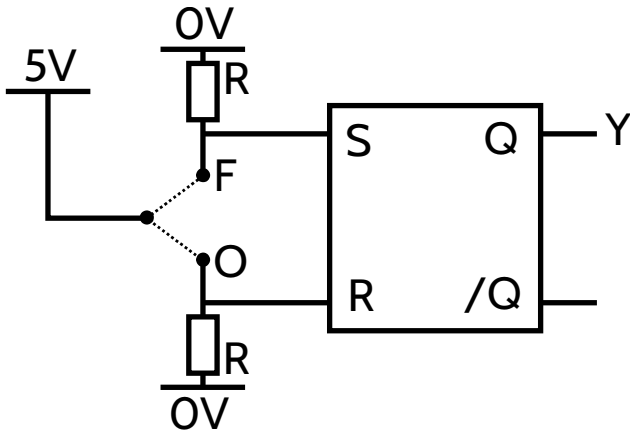
| S | R | Q         |
|---|---|-----------|
| 0 | 0 | inchangée |
| 0 | 1 | 0         |
| 1 | 0 | 1         |
| 1 | 1 | interdit  |

# Le bistable RS

- On constate que pour un état des entrées ( $S=R=0$ ), il existe deux états de sortie possible :  $Q=0$  ou  $Q=1$
- On appelle système logique séquentiel tout système qui admet pour un état d'entrée plusieurs états de sorties possibles. La sortie est fonction des entrées mais aussi de ce qui s'est passé auparavant.

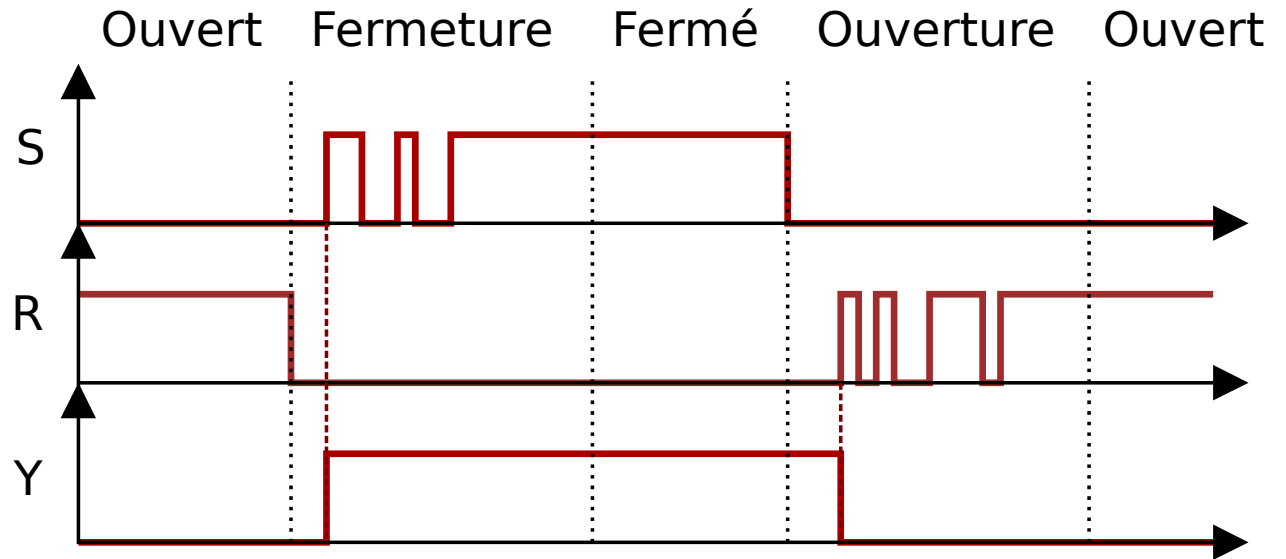
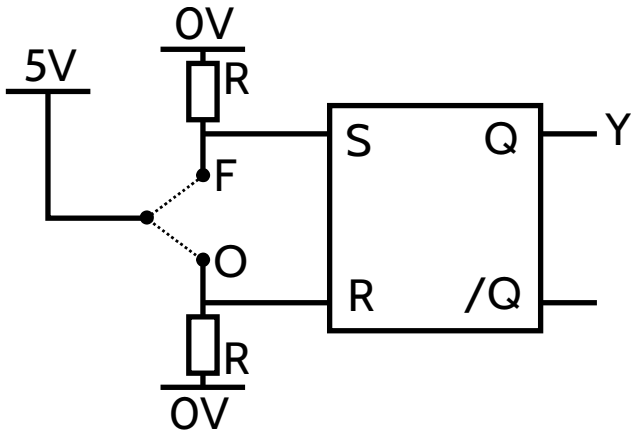
| S | R | Q         |
|---|---|-----------|
| 0 | 0 | inchangée |
| 0 | 1 | 0         |
| 1 | 0 | 1         |
| 1 | 1 | interdit  |

# Le bistable RS - exercice

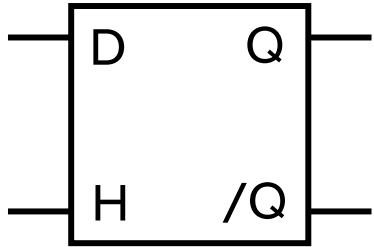




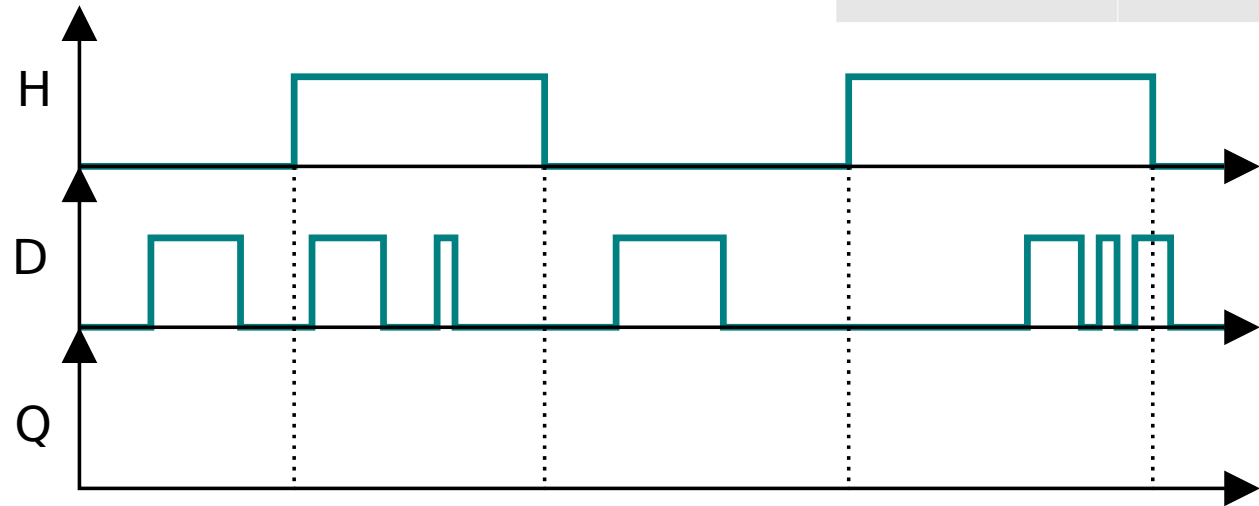
# Le bistable RS - exercice



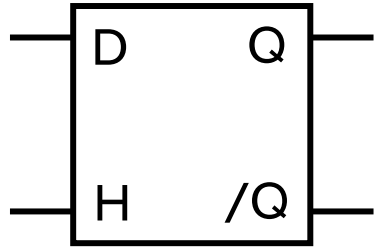
# Le verrou (latch) D



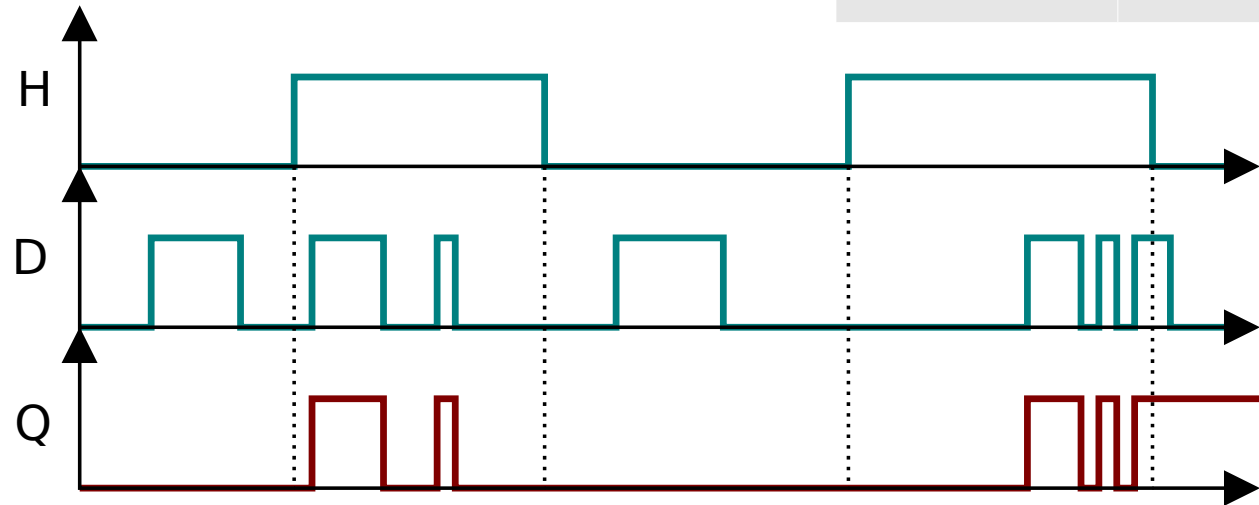
| H | Q         |
|---|-----------|
| 0 | Inchangée |
| 1 | D         |



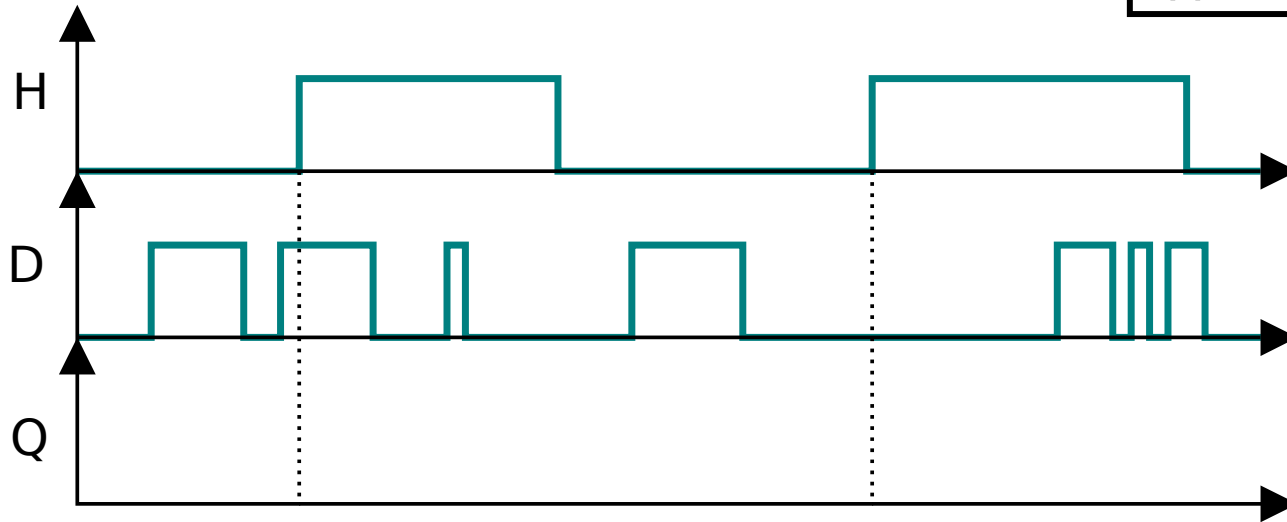
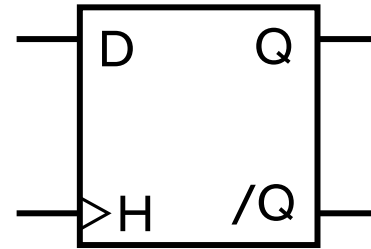
# Le verrou (latch) D



| H | Q         |
|---|-----------|
| 0 | Inchangée |
| 1 | D         |



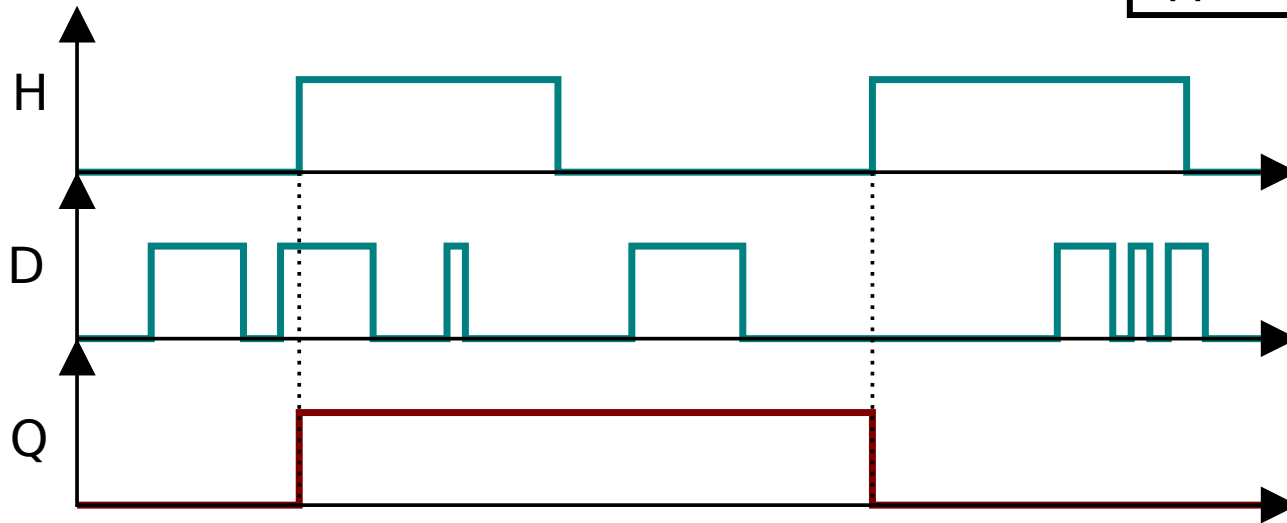
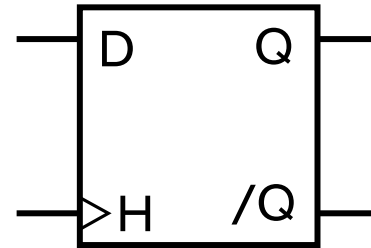
# La bascule D



| H   | $D_n$ | $Q_{n+1}$ |
|-----|-------|-----------|
| 0/1 | X     | $Q_n$     |
| ↑   | 0     | 0         |
| ↑   | 1     | 1         |

| H   | $Q_{n+1}$ |
|-----|-----------|
| 0/1 | $Q_n$     |
| ↑   | $D_n$     |

# La bascule D



| H   | $D_n$ | $Q_{n+1}$ |
|-----|-------|-----------|
| 0/1 | X     | $Q_n$     |
| ↑   | 0     | 0         |
| ↑   | 1     | 1         |

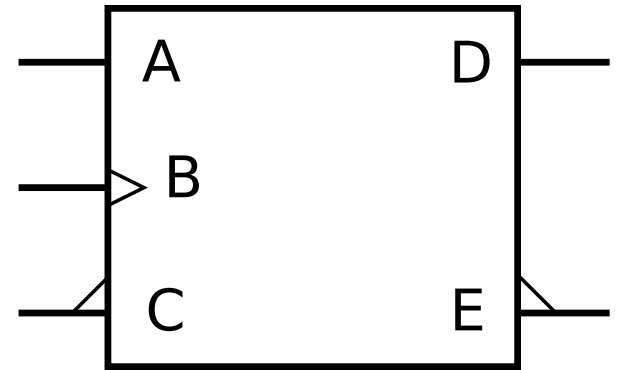
| H   | $Q_{n+1}$ |
|-----|-----------|
| 0/1 | $Q_n$     |
| ↑   | $D_n$     |

# La bascule D

- On constate que la sortie Q recopie l'entrée D à chaque front montant de l'horloge
- Système synchrone
  - Tout système disposant d'une entrée « horloge » qui fixe les instants des éventuels changements des sorties

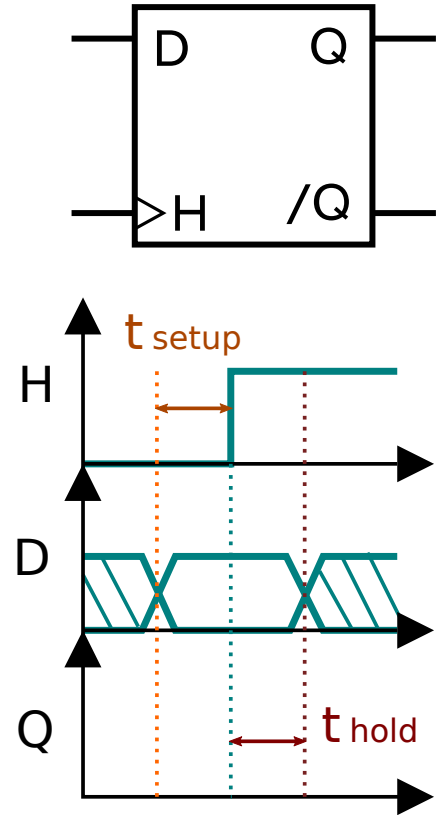
# La bascule D

- Notations
  - A est un entrée classique
  - B est une horloge (entrée)
  - C est une entrée complémentée
  - D est une sortie classique
  - E est une sortie complémentée



# La bascule D

- Pour assurer le fonctionnement correct de la bascule
- $t_{\text{setup}}$  ou  $t_{\text{su}}$  : temps de prépositionnement
  - Temps avant le front d'horloge pendant lequel la donnée doit être stable
- $t_{\text{hold}}$  ou  $t_{\text{h}}$  : temps de maintien
  - Temps après le front d'horloge pendant lequel la donnée doit être stable





# La bascule D

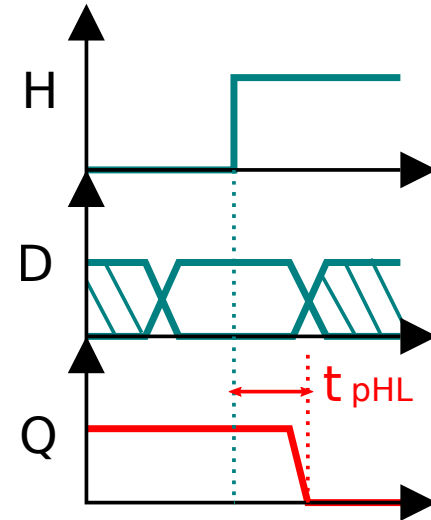
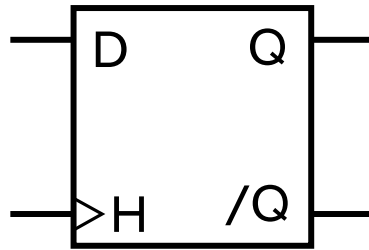
- $t_p$  : temps de propagation

- $t_{pHL}$

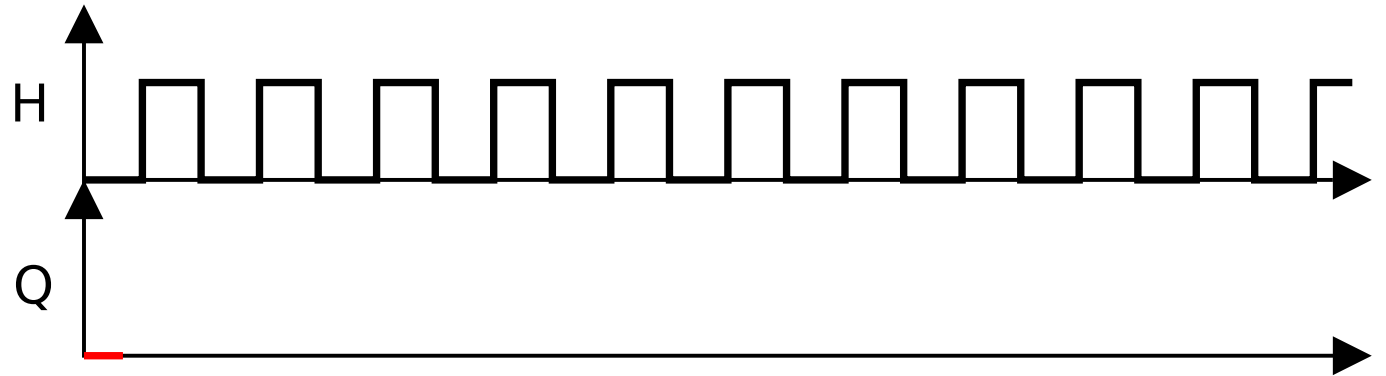
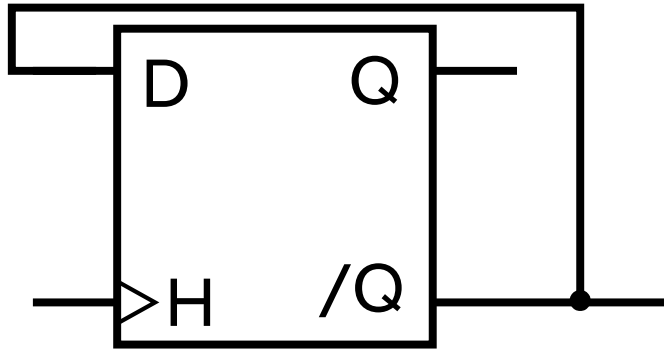
- High to Low

- $t_{pLH}$

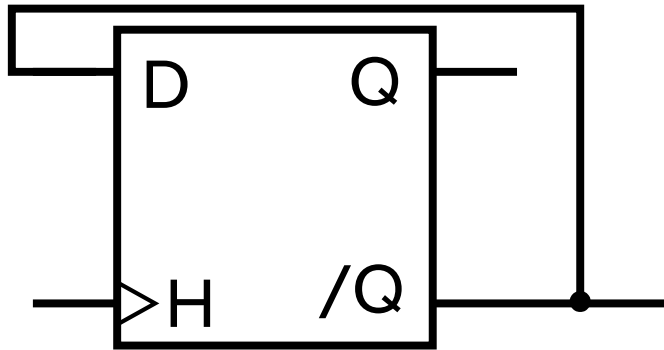
- Low to High



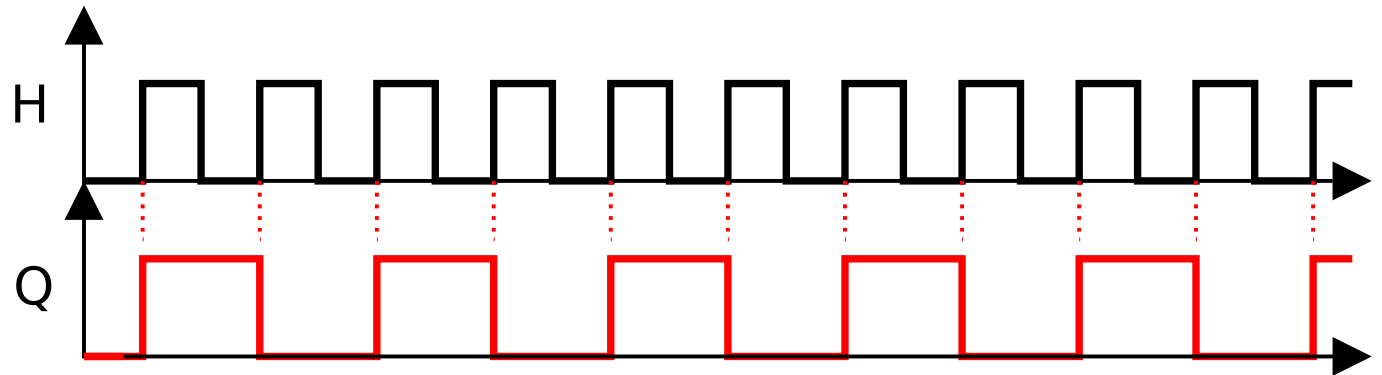
# La bascule D - exercice 1



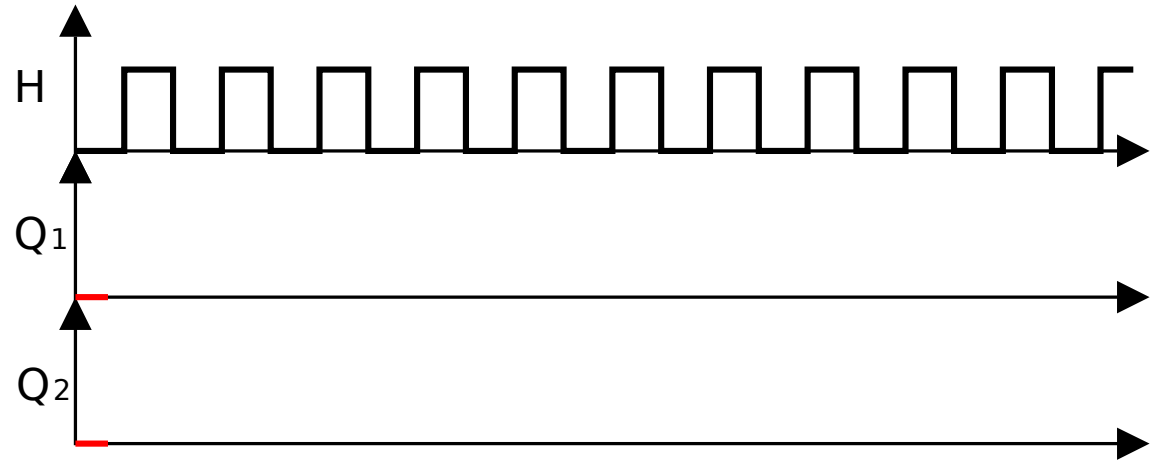
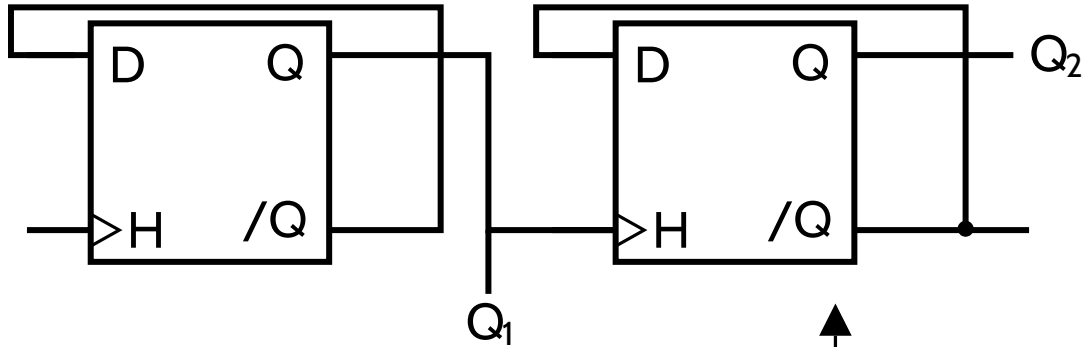
# La bascule D - exercice 1



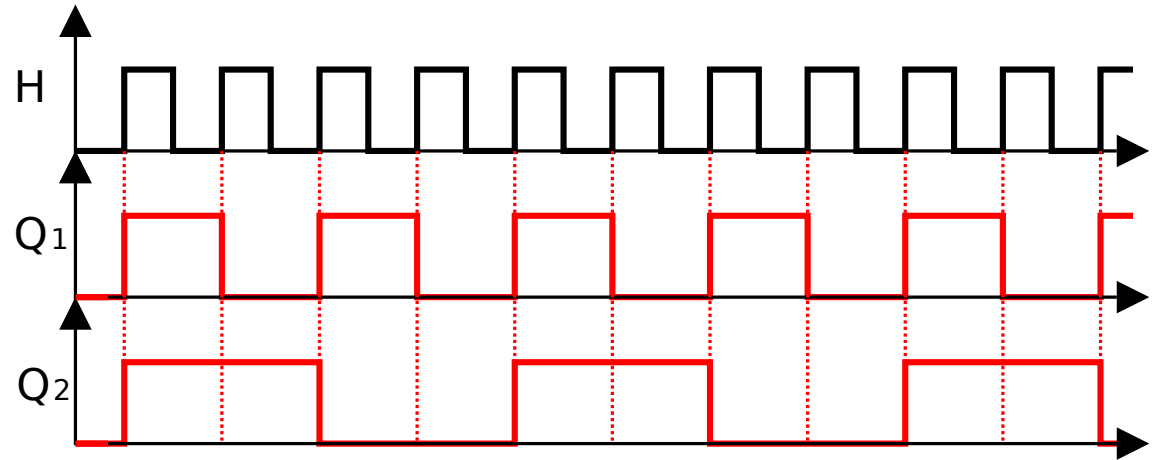
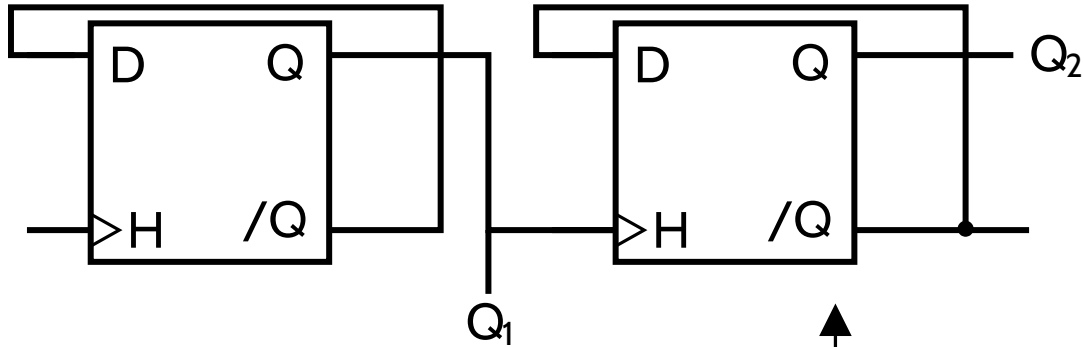
La fréquence du signal  $F_q = F_H/2$



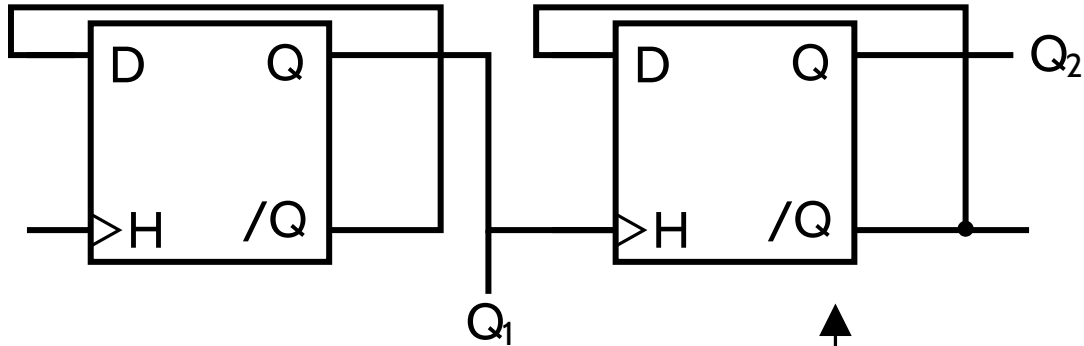
# La bascule D – exercice 2



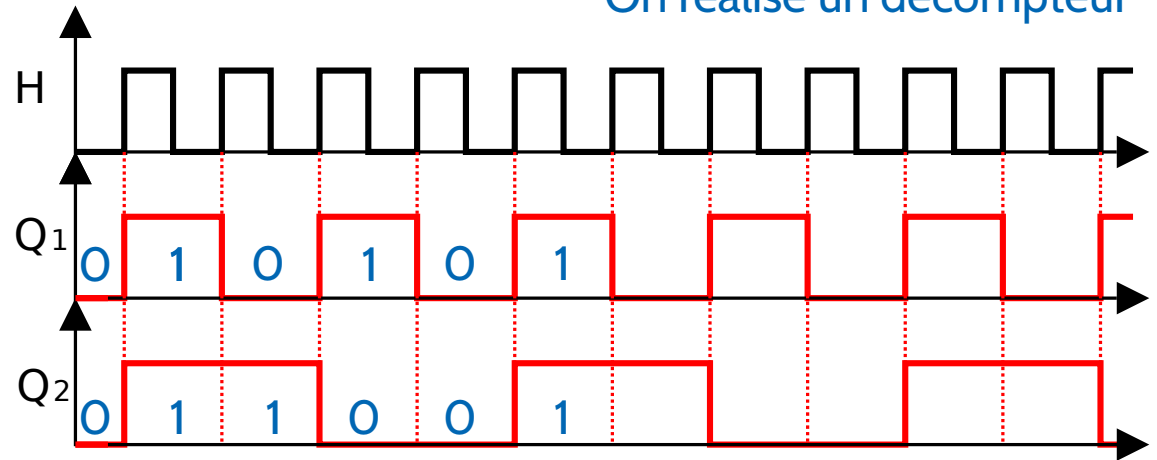
# La bascule D – exercice 2



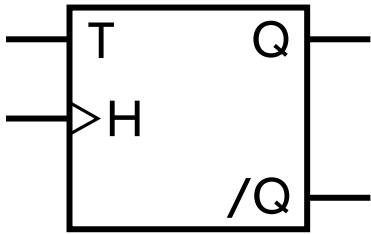
# La bascule D – exercice 2



On réalise un décompteur

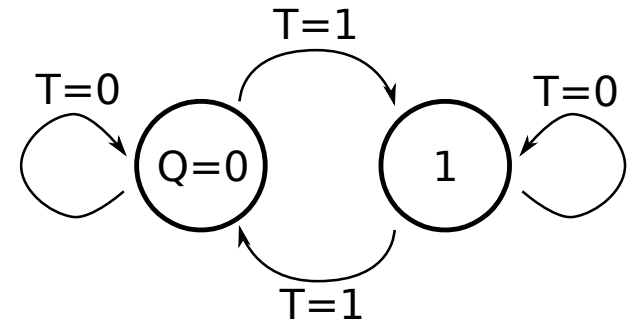


# La bascule T

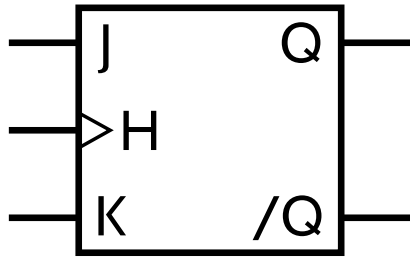


| H   | T   | $Q_{n+1}$ |
|-----|-----|-----------|
| 0/1 | 0/1 | $Q_n$     |
| ↑   | 0   | $Q_n$     |
| ↑   | 1   | $/Q_n$    |

Diagramme des états de la bascule T

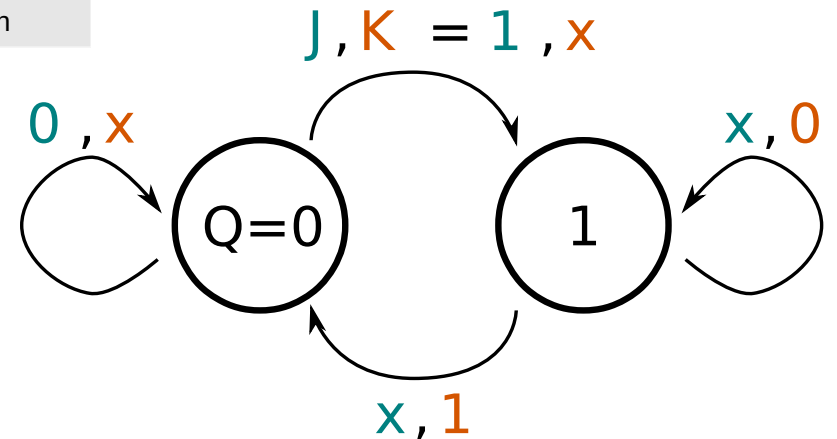


# La bascule JK



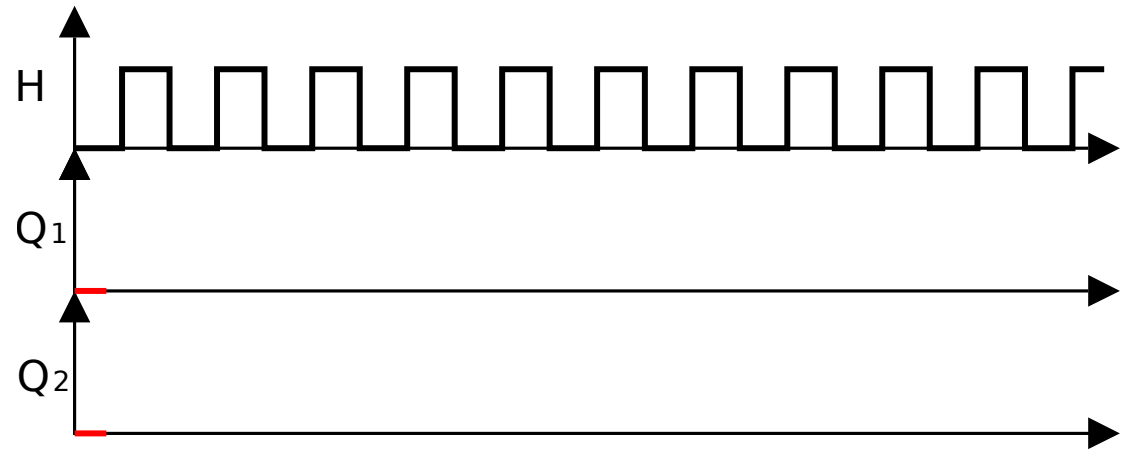
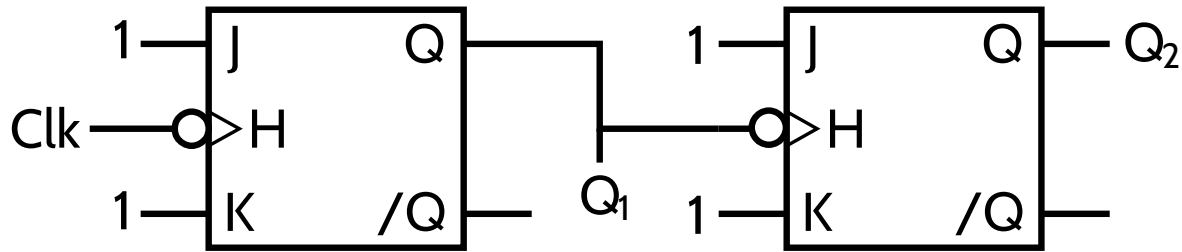
| J | K | $Q_{n+1}$  |
|---|---|------------|
| 0 | 0 | $Q_n$      |
| 0 | 1 | 0          |
| 1 | 0 | 1          |
| 1 | 1 | $\neg Q_n$ |

Diagramme des états de la bascule JK

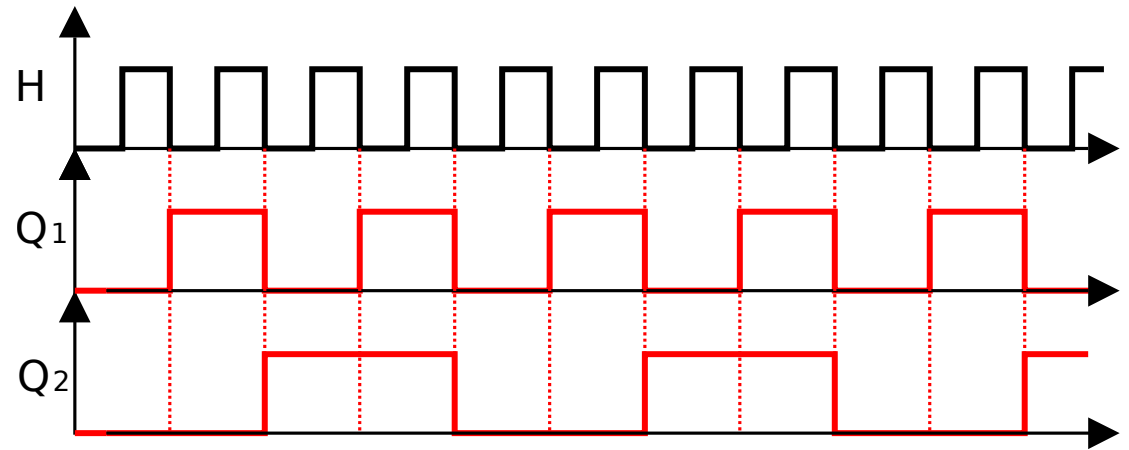
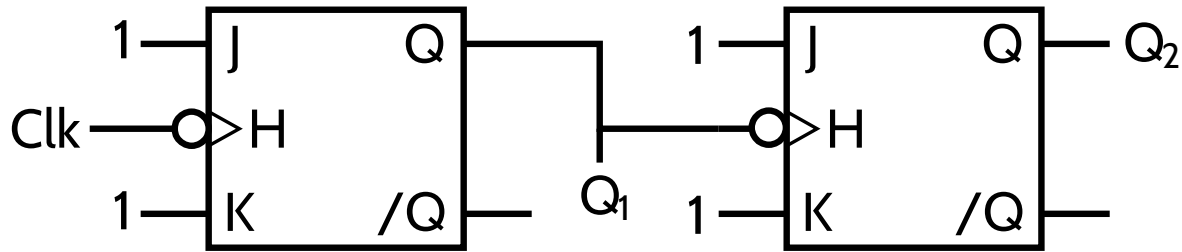




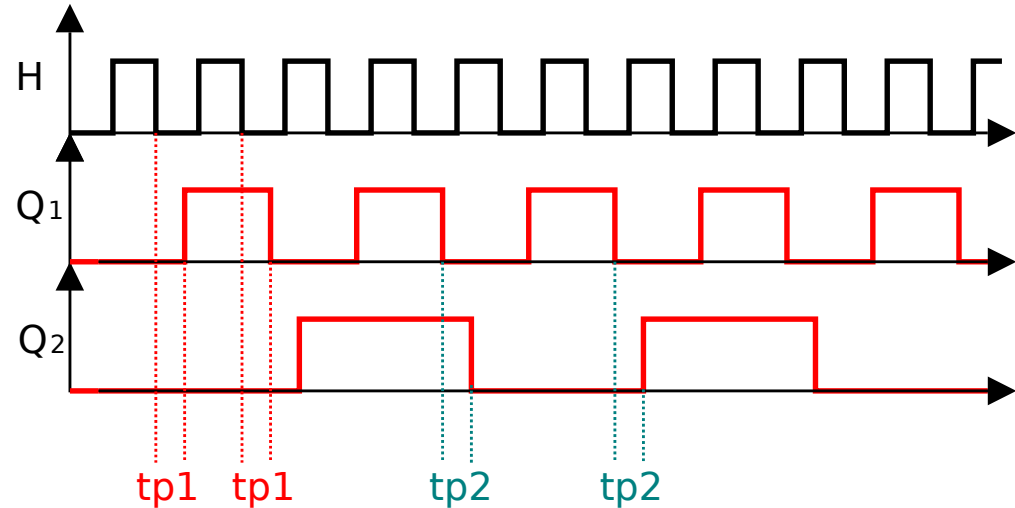
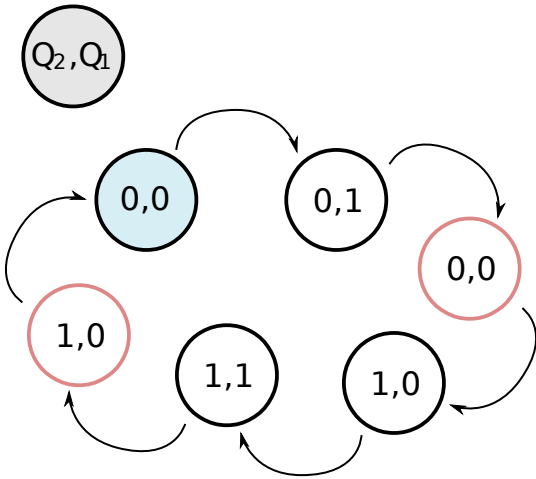
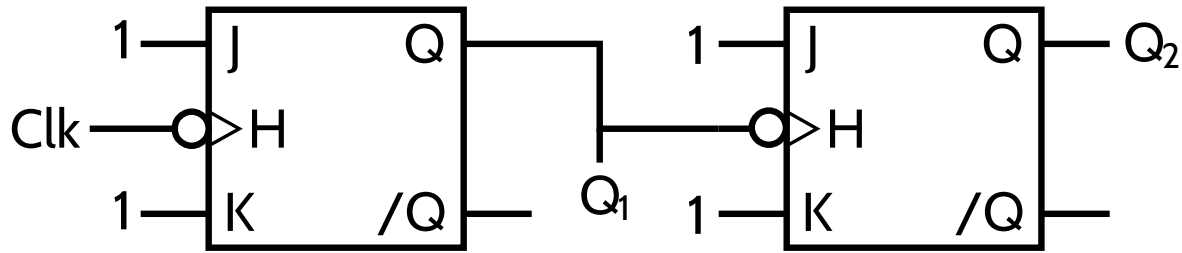
# La bascule JK : exercices



# La bascule JK : exercices

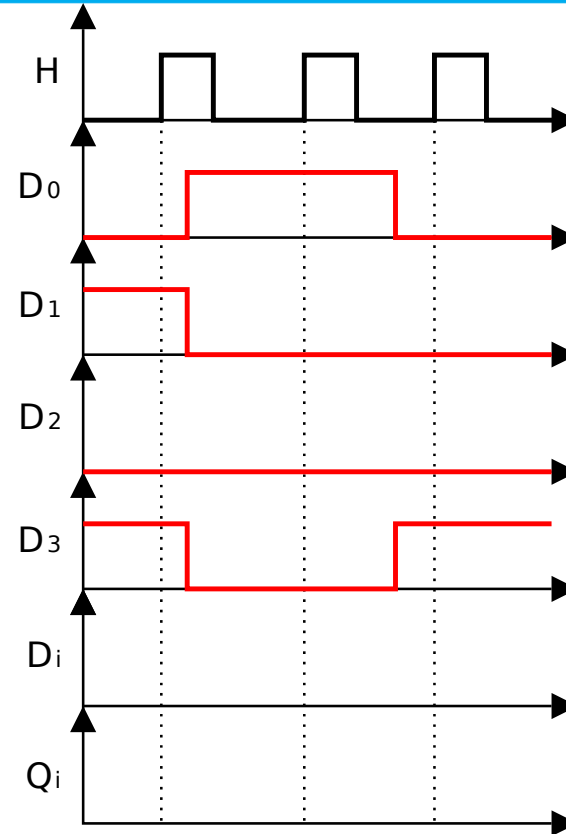
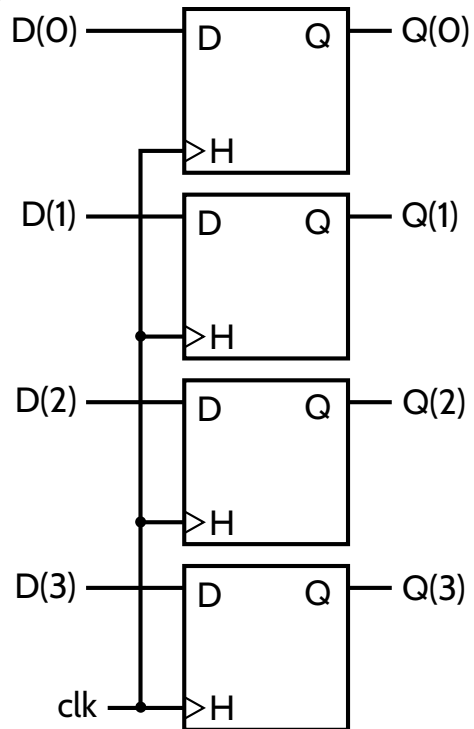


# La bascule JK : exercices



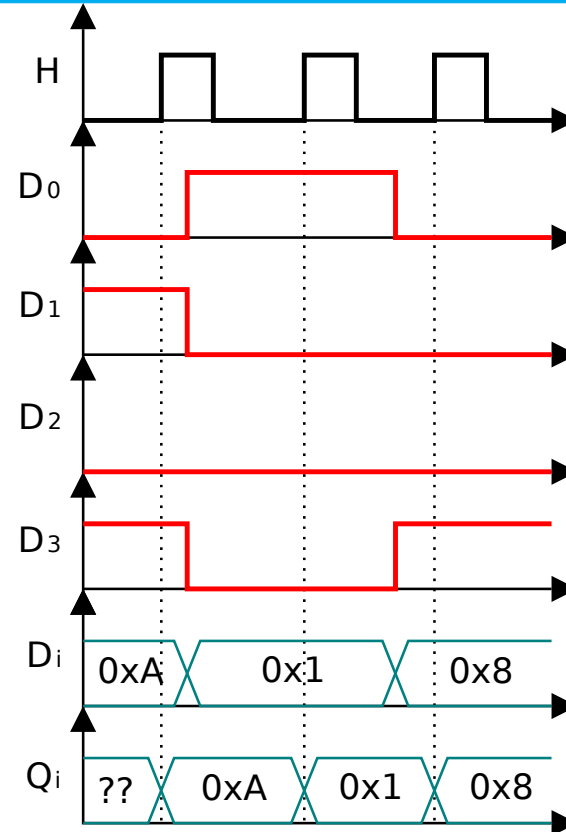
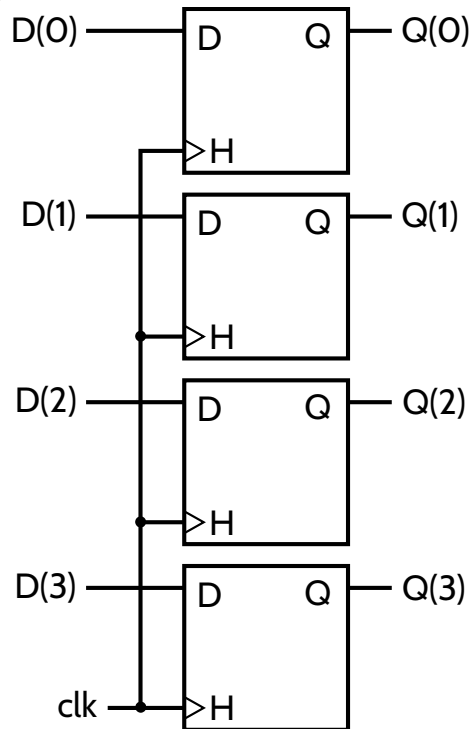
# Exemples d'utilisation des bascules

- Registre mémoire



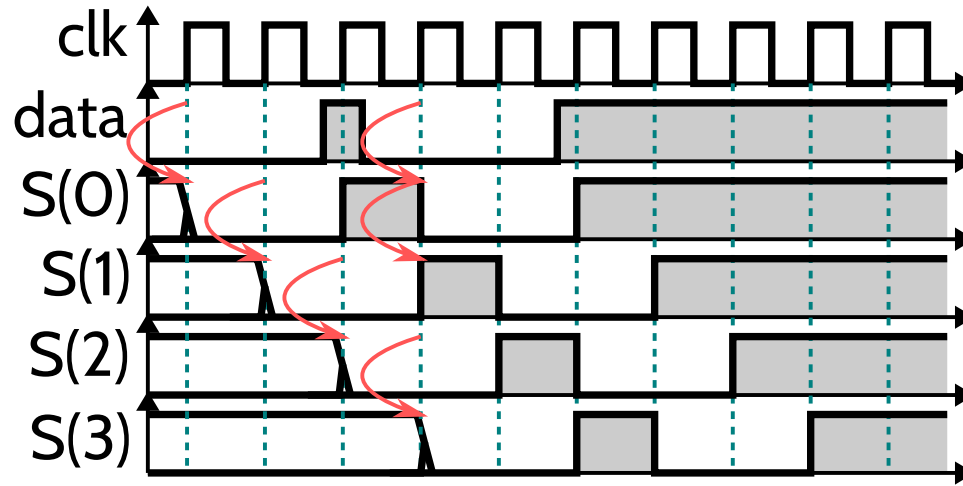
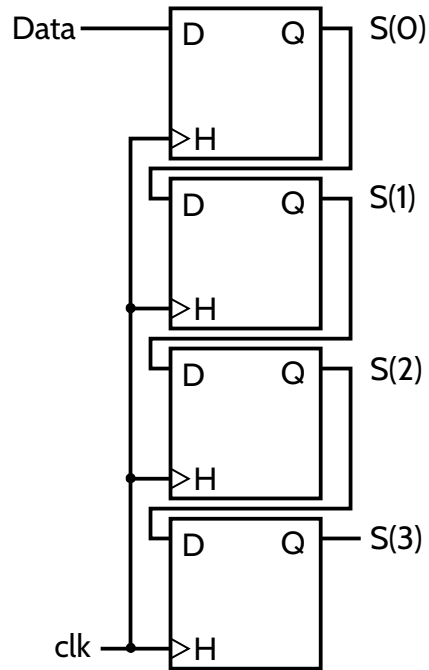
# Exemples d'utilisation des bascules

- Registre mémoire



# Exemples d'utilisation des bascules

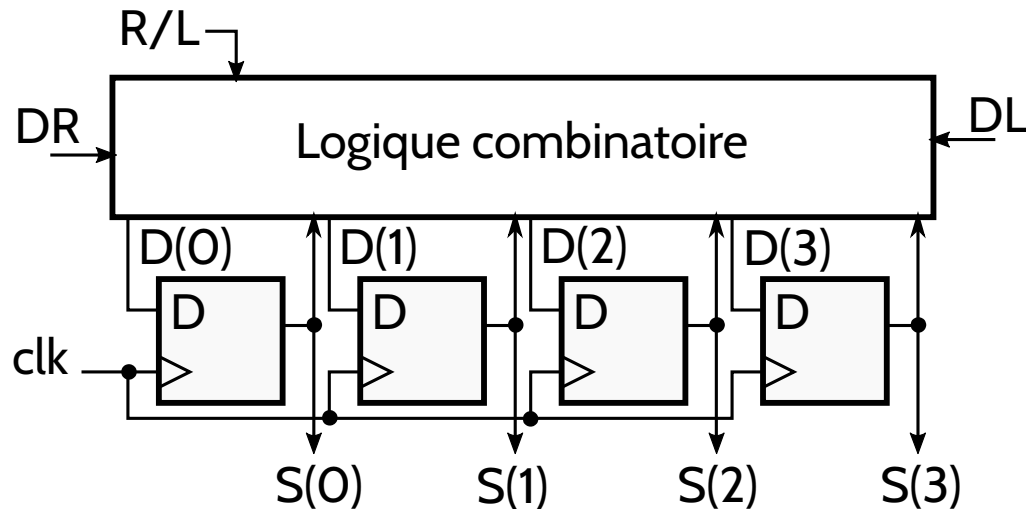
- Registre à décalage



| Data | S(0) | S(1) | S(2) | S(3) |
|------|------|------|------|------|
| 0    | x    | x    | x    | x    |
| 0    | 0    | x    | x    | x    |
| 0    | 0    | 0    | x    | x    |
| 1    | 0    | 0    | 0    | x    |
| 0    | 1    | 0    | 0    | 0    |
| 0    | 0    | 1    | 0    | 0    |
| 1    | 0    | 0    | 1    | 0    |
| 1    | 1    | 0    | 0    | 1    |
| 1    | 1    | 1    | 0    | 0    |
| 1    | 1    | 1    | 1    | 0    |

# Exemples d'utilisation des bascules

- Registre à décalage
  - Certains registres permettent le décalage vers la gauche ou vers la droite



$$D(0) = R/L \cdot DR + \overline{R/L} \cdot S(1)$$

$$D(1) = R/L \cdot S(0) + \overline{R/L} \cdot S(2)$$

...

$$D(3) = R/L \cdot S(2) + \overline{R/L} \cdot DL$$